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Saeed B. Niku is the author of Introduction to Robotics: Analysis, Control, Applications, 2nd Edition, published by Wiley.

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kinematics, dynamics, control, sensing, and planning for robot manipu-lators. Given the state of maturity of the subject and the vast diversity of stu-dents who study this material, we felt the need for a book which presents a slightly more abstract (mathematical) formulation of the kinematics, dynamics, and control of robot manipulators.

A Mathematical Introduction to Robotic Manipulation

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